

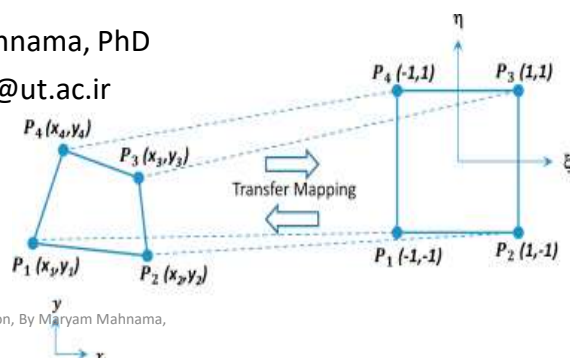


Chapter 9: Isoparametric Formulation

Development of Bar Element Formulation

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Motivation



- Development of element matrices in terms of a global coordinate system becomes an enormously difficult task (if even possible) except for the simplest of elements such as the CST.
- The isoparametric method may appear somewhat confusing initially, but it will lead to a simple computer program formulation
- It is generally applicable for 2D and 3D stress analysis and for nonstructural problems.
- The isoparametric formulation allows elements to be created that are nonrectangular and have curved sides.
- Furthermore, numerous commercial computer programs have adapted this formulation for their various libraries of elements



Contents of This Chapter



- The isoparametric formulation to develop the simple bar element stiffness matrix.
- Development of the rectangular plane stress element stiffness matrix in terms of a global-coordinate system.
- The isoparametric formulation of the simple quadrilateral element stiffness matrix,



Isoparametric Formulation of the Bar Element Stiffness Matrix

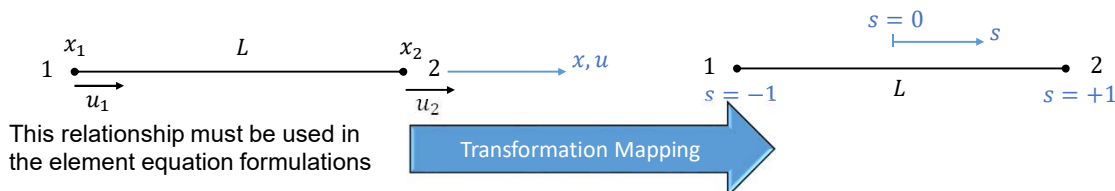


- The term isoparametric is derived from the use of the same shape functions $[N]$ to define the element's geometric shape as are used to define the displacements within the element

$$u = N_1 u_1 + N_2 u_2$$

$$x = N_1 x_1 + N_2 x_2$$

Isoparametric element equations are formulated using a natural (or intrinsic) coordinate system s that is defined by element geometry and not by the element orientation in the global-coordinate system



This relationship must be used in the element equation formulations



Development of the Isoparametric Formulation for the Bar Element



- Step 1: Select Element Type
- Step 2: Select a Displacement Function
- Step 3: Define the Strain/Displacement & Stress/Strain Relationships
- Step 4: Derive the Element Stiffness Matrix and Equations

$$x = x_c + \frac{L}{2}s$$

s and x can be related. The natural coordinate s is attached to the element, with the origin located at the center of the element.

$$x = \frac{x_1 + x_2}{2} + \frac{x_2 - x_1}{2}s$$

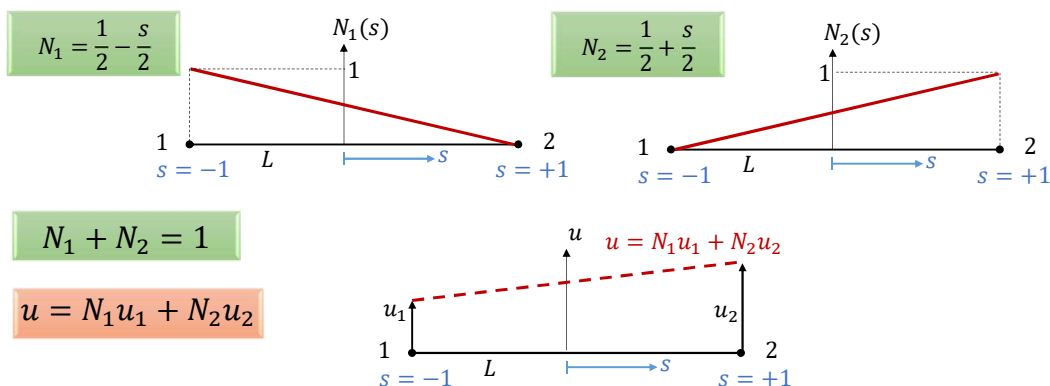
$$x = \underbrace{\left(\frac{1-s}{2}\right)}_{N_1} x_1 + \underbrace{\left(\frac{1+s}{2}\right)}_{N_2} x_2$$

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Development of the Isoparametric Formulation for the Bar Element (Step1)



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Development of the Isoparametric Formulation for the Bar Element (Step1)



- Another approach to find the shape functions:

We have 2 components to define the geometry of element: x_1, x_2

$$x(s) = a_1 + a_2 s$$



$$x(-1) = a_1 - a_2 = x_1$$

$$x(+1) = a_1 + a_2 = x_2$$



$$x = \underbrace{\left(\frac{1-s}{2}\right)}_{N_1} x_1 + \underbrace{\left(\frac{1+s}{2}\right)}_{N_2} x_2$$

$$x = [N_1 \quad N_2] \begin{Bmatrix} x_1 \\ x_2 \end{Bmatrix}$$

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Development of the Isoparametric Formulation for the Bar Element (Step2)



- Step 2: Select a Displacement Function
- The displacement function within the bar is now defined by the same shape functions:

$$u = [N_1 \quad N_2] \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix}$$

Since u and x are defined by the same shape functions at the same nodes, the element is called isoparametric

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Development of the Isoparametric Formulation for the Bar Element (Step3)



- Step 3: Define the Strain/Displacement & Stress/Strain Relationships

We now want to formulate element matrix [B] to evaluate [k].

⇒ We need the expression for strain

$$\epsilon_x = \frac{du}{dx} \quad \Rightarrow \quad \epsilon_x = \frac{du}{dx} = \begin{bmatrix} \frac{dN_1}{dx} & \frac{dN_2}{dx} \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} \quad \Rightarrow \quad \epsilon_x = \frac{2}{L} \begin{bmatrix} \frac{dN_1}{ds} & \frac{dN_2}{ds} \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix}$$

N_1 and N_2 are functions of s , not x

$$u = [N_1 \quad N_2] \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} \quad \Rightarrow \quad \frac{du}{dx} = \frac{du/ds}{dx/ds} \quad \Rightarrow \quad \frac{du}{dx} = \frac{2}{L} \frac{du}{ds}$$

$$\frac{dx}{ds} = \frac{dN_1}{ds} x_1 + \frac{dN_2}{ds} x_2 = \frac{x_2 - x_1}{2} = \frac{L}{2}$$

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Development of the Isoparametric Formulation for the Bar Element (Step3)



$$\epsilon_x = \frac{2}{L} \begin{bmatrix} -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} \quad \Rightarrow \quad \epsilon_x = \begin{bmatrix} -\frac{1}{L} & \frac{1}{L} \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix}$$

$[B]$

$$\sigma_x = E \epsilon_x = E[B]\{d\}$$

- Step 4: Derive the Element Stiffness Matrix and Equations

$$[k] = \int_0^L [B]^T E [B] A dx$$

in general, we must transform the coordinate x to s because $[B]$ is, in general, a function of s .

$$\int_0^L f(x) dx = \int_{-1}^1 f(s) \det([J]) ds$$

$$\det([J]) = \frac{dx}{ds} = \frac{L}{2}$$

Jacobian Matrix

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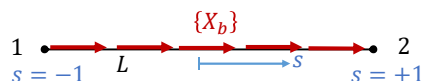


Development of the Isoparametric Formulation for the Bar Element (Step4)



$$[k] = \int_{-1}^1 [B]^T E [B] A \frac{L}{2} ds = \int_{-1}^1 \begin{Bmatrix} -\frac{1}{L} \\ 1 \\ \frac{1}{L} \end{Bmatrix} E \begin{bmatrix} -\frac{1}{L} & \frac{1}{L} \end{bmatrix} A \frac{L}{2} ds \Rightarrow [k] = \frac{AE}{L} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}$$

- Body force in isoparametric formulation:



$$\{f_b\} = \int_{-1}^1 [N]^T \{X_b\} A \frac{L}{2} ds \Rightarrow \{f_b\} = \int_{-1}^1 [N]^T \{X_b\} A \frac{L}{2} ds$$

Function of s, not x X_B should also be expressed in terms of s



Force Calculation in Isoparametric Formulation (Example)

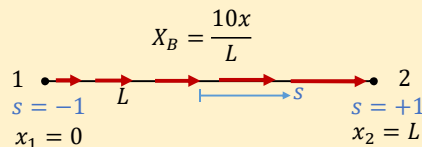


- Example: we can assume body force as

$$X_B = \frac{10x}{L} = \frac{10}{L} (N_1 x_1 + N_2 x_2) = \frac{5}{L} [(1-s)x_1 + (1+s)x_2]$$

$$X_B = 5(1+s)$$

$$\{f_b\} = \int_{-1}^1 \begin{Bmatrix} \frac{1-s}{2} \\ 1 \\ \frac{1+s}{2} \end{Bmatrix} 5(1+s) A \frac{L}{2} ds = \frac{5AL}{3} \begin{Bmatrix} 1 \\ 2 \end{Bmatrix}$$



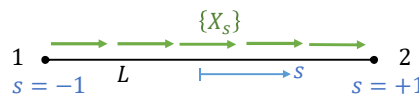


Force Calculation in Isoparametric Formulation



- Surface force in isoparametric formulation:

$$\{f_s\} = \iint [N_s]^T \{X_s\} dS$$



Assuming the cross section is constant and the traction is uniform over the perimeter and along the length of the element,

$$\{f_s\} = \int_0^L [N_s]^T \{X_s\} dx$$

Function of s, not x



$$\{f_s\} = \int_{-1}^1 [N_s]^T \{X_s\} \frac{L}{2} ds$$

X_B should also be expressed in terms of s



Force Calculation in Isoparametric Formulation (Example)

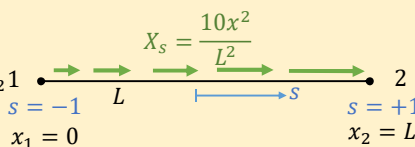


- Example: we can assume surface force as

$$X_s = \frac{10x^2}{L^2} = \frac{10}{L^2} (N_1 x_1 + N_2 x_2)^2 = \frac{5}{2L^2} [(1-s)x_1 + (1+s)x_2]^2$$

$$X_s = \frac{5}{2} (1+s)^2$$

$$\{f_s\} = \int_{-1}^1 \begin{Bmatrix} \frac{1-s}{2} \\ \frac{1+s}{2} \end{Bmatrix} \frac{5}{2} (1+s)^2 A \frac{L}{2} ds = \frac{5AL}{2} \begin{Bmatrix} \frac{1}{3} \\ 1 \end{Bmatrix}$$





Summary



- Plane Strain and Plane Stress Formulations can be used for LST Element.
- LST Element was defined and the displacement functions were extracted.
- Stiffness matrix for LST element can be derived using numerical integration.